LAMPIRAN

```
#include <SoftwareSerial.h>

SoftwareSerial bluetooth(0, 1); // RX, TX

void setup() {
  bluetooth.begin(9600);
  Serial.begin(9600);
  pinMode(10, OUTPUT); // Pin untuk kontrol motor
  pinMode(11, OUTPUT);
  pinMode(12, OUTPUT);
  pinMode(13, OUTPUT);
}

void loop() {
  if (bluetooth.available()) {
    char command = bluetooth.read();
    if (command == 'F') {
      // Maju
      digitalWrite(10, HIGH);
      digitalWrite(11, LOW);
      digitalWrite(12, HIGH);
      digitalWrite(13, LOW);
    } else if (command == 'B') {
      // Mundur
      digitalWrite(10, LOW);
```

```cpp
    digitalWrite(11, HIGH);

    digitalWrite(12, LOW);

    digitalWrite(13, HIGH);

  } else if (command == 'L') {

    // Kiri

    digitalWrite(10, LOW);

    digitalWrite(11, HIGH);

    digitalWrite(12, HIGH);

    digitalWrite(13, LOW);

  } else if (command == 'R') {

    // Kanan

    digitalWrite(10, HIGH);

    digitalWrite(11, LOW);

    digitalWrite(12, LOW);

    digitalWrite(13, HIGH);

  } else if (command == 'S') {

    // Stop

    digitalWrite(10, LOW);

    digitalWrite(11, LOW);

    digitalWrite(12, LOW);

    digitalWrite(13, LOW);

  }

 }

}
```